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1. **LOST: localization-space trails for robot teams**
   Vaughan, R.T.; Stoy, K.; Sukhatme, G.S.; Mataric, M.J.;
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2. **Augmented reality for programming industrial robots**
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3. **Predictive robot programming**
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4. **Optimization of waypoint-guided potential field navigation using evolutionary algorithms**
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   Intelligent Robots and Systems, 2004. (IROS 2004). Proceedings. 2004 IEEE/RSJ International Conference on
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5. **Exploration of Teisi Knoll by autonomous underwater vehicle "R-One robot"**
   Ura, T.; Obara, T.; Takagawa, S.; Gamo, T.;
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   Volume 1, 5-8 Nov. 2001 Page(s):456 - 461 vol.1
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8. **Method and system for robot end effector path correction using 3-D ultrasound sensors**
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19. **Towards real-world searching with fixed-wing mini-UAVs**
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